Faster Thermoviscous Acoustic Simulations

For Micro-Acoustics

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1/21





COMSOL implementation, and verification

Onclusions

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- Many devices related to hearing and sound contain narrow ducts for propagating sound to/from the ear. I.e:
 - Hearing aids
 - Earbuds
 - Hearing protection
- These narrow ducts introduce thermoviscous damping of acoustic waves.
- These effects need to be taken into account in the modeling.
 - COMSOL Thermoviscous Acoustics Physics Interface = numerically expensive
 - Other methods
 - ★ Boundary Layer Impedance \Rightarrow only for wide geometries
 - ★ Narrow Region Acoustics \Rightarrow only for prismatic geometries







• Important parameters:

- Viscous penetration depth: δ_{ν}
- Thermal penetration depth: δ_κ

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COMSOL implementation, and verification

Onclusions

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- Start with, a Newtonian ideal gas, the governing equations are continuity, momentum and the energy equation, closed with the ideal gas equation of state. No external forces, heat sources and negligible gravity.
- Assume small perturbation in time harmonic form. No mean flow, uniform mean temperature and pressure. Then one ends with the Linearized Navier Stokes equations:

$$i\omega\rho + \rho_0 \nabla \cdot \boldsymbol{u} = 0$$
 \Leftarrow continuity, (1)

$$i\omega\rho_0 \boldsymbol{u} = -\nabla \boldsymbol{p} + \nabla \cdot \boldsymbol{\tau}$$
 \Leftarrow momentum, (2)

$$\rho_0 c_{\rho} i\omega T = i\omega p + \kappa \nabla^2 T \qquad \qquad \Leftarrow \text{energy}, \tag{3}$$

where:

- u: Acoustic velocity phasor [m/s]
- ρ : Acoustic density phasor [kg/m³]
- *i*: $\sqrt{-1}$, ω : Radian frequency [rad/s]
- p: Acoustic pressure phasor [Pa]
- c_p: Specific heat at constant pressure [J/kgK]

- T: Acoustic temperature phasor [K]
- κ: Thermal conductivity [W/mK]
- T_0 , p_0 , ρ_0 : Mean values in the field of above described quantities.
- And:

$$\boldsymbol{\tau} = \mu \nabla^2 \boldsymbol{u} + (\lambda + \mu) \nabla (\nabla \cdot \boldsymbol{u})$$

• Where: μ : dynamic viscosity [Pa·s], λ : Second viscosity [Pa·s].



- To further derive the model, some simplifications are required. The justification of these assumptions is described in detail by R. Kampinga [2, 3, 1]. It is based on a order-of-magnitude analysis and some further assumptions generally applicable in micro-acoustic geometries.
- Apply the following assumptions:
 - > The divergence of the velocity field is much smaller than typical single gradients of the velocity field.
 - ▶ On the scale of viscothermal boundary gradients, the acoustic pressure is more/less constant.
- Then, we can write for the momentum equation:

$$\boldsymbol{u} = \frac{i}{\omega\rho_0} \left(1 - \boldsymbol{h}_{\nu} \right) \nabla \boldsymbol{p},\tag{5}$$

where h_{ν} satisfies:

$$\nabla^2 h_{\nu} + \frac{2i}{\delta_{\nu}^2} h_{\nu} = 0, \tag{6}$$

and is defined as the "viscous field", where:

$$\delta_{\nu}^{2} = \frac{2\mu}{\rho_{0}\omega} \tag{7}$$

• Close to a wall, $h_{\nu} \rightarrow 1$, such that the velocity does not follow the pressure gradient anymore. Far from a wall, $h_{\nu} \rightarrow 0$, such that the inviscid case is retrieved back.

Dr.ir. Anne de Jong	Faster Thermoviscous Acoustic Simulations	October 25, 2023	7 / 21



- Apply the following assumption to the energy equation:
 - > On the scale of viscothermal boundary gradients, the acoustic pressure is more/less constant.
- Then, we can write for the energy equation:

$$T = \frac{\rho}{\rho_0 c_\rho} \left(1 - h_\kappa\right) \tag{8}$$

where h_{κ} satisfies:

$$\nabla^2 h_{\kappa} + \frac{2i}{\delta_{\kappa}^2} h_{\kappa} = 0, \tag{9}$$

and is defined as the "thermal field", where:

$$\delta_{\kappa}^{2} = \frac{2\kappa}{\rho_{0}c_{p}\omega} \tag{10}$$

• Close to a wall, $h_{\kappa} \rightarrow 1$, such that the temperature oscillation goes to 0. Far from a wall, $h_{\kappa} \rightarrow 0$, such that the temperature oscillation responds adiabatically to a pressure oscillation.

- Eliminate the density by using the equation of state.
- Fill in for the momentum equation in *u*
- Fill in for the temperature the heat equation
- The we find:

$$\nabla \cdot ((1 - h_{\nu}) \nabla p) + k^2 (1 + (\gamma - 1) h_{\kappa}) p = 0,$$
(11)

where:

$$k = \omega/c_0$$
,

and

$$\gamma = c_p \left(c_p - R_s \right), \tag{12}$$

the ratio of specific heats.

• This is an "almost"-Helmholtz equation that can be solved in the same way as the inviscid Helmholtz is already solved in the current "Pressure Acoustics" physics interface.







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Onclusions

Dr.ir. Anne de Jong

10/21

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Propagating wave in infinite duct



- Start with something we know a solution of, before exploring the unknown.
- \bullet This is a square duct. Length 1 m, cross section 1x1 mm.
 - These dimensions are such small, that wave damping will lower the amplitude.
- The figure below shows the mesh. Note that boundary layers are required when solving with SLNS.















• Adjusted Helmholtz equation incorporating viscous and thermal fields:

$$\nabla \cdot ((1 - h_{\nu}) \nabla p) + k^2 (1 + (\gamma - 1) h_{\kappa}) p = 0.$$
(15)

- We tried to implement this as COMSOL-compatible as possible. So instead of creating a new "General PDE". We tweaked the pressure acoustic interface with a weak contribution.
- It means, splitting up the existing pressure acoustics terms, from the new ones and only adding the new ones.



Pressure Acoustics, Frequency Domain (acpr)	Veak Contribution
🔻 🔚 Domains	
Pressure Acoustics 1	Label: Weak Contribution 1
Initial Values 1	Domain Selection
Heak Contribution 1	Override and Contribution
Boundaries	- Wath Castellution
Sound Hard Boundary (Wall) 1	* Weak Contribution
Interior Impedance 1	Weak expression:
🕨 🥅 Pressure 1	(hnu*(test(px)*px+test(py)*py+test(pz)*pz)+p*test(p)*acpr.ik^2*(1-gamma)*hkappa)*acpr.delta/acpr.rho_c
🗁 Edges	
🧮 Points	
Global	🗹 Use automatic quadrature settings
But Equation View	



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- To force COMSOL solving this problem sequentially, there are multiple options:
 - Create separate study steps, in which each of the field is solved, and the use the result of the viscous and termal fields as "Values of variables not solved for".
 - Replace the default "Fully coupled" solver with a segregated solver. Configure the segregated solver to apply only a single step for all the fields (as it is a sequentially and linear problem).
- Vite 51,15
 Step 1: Frequency Domain
 No. Solver Configurations
 Old Solution 1 (init)
 Constant Solver 1
 Outstant Solver 1
 Outstant Solver 1
 Parametrix 1
 Param

- Here, we choose option 2.
- The first method has as disadvantage that, when performing frequency sweeps, a solution for the viscous and thermal fields needs to be picked correcty, i.e. for frequency x of the Helmholtz solution, also frequency x of the viscous and thermal field solutions should be used. This method is therefore a bit more prone to errors.

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Compute to Selected E Compute

Dependent variable hkappa (comp1.hkappa)

Constant (Newton)

On every iteration

El Uodate automatic scale factors in weights

Termination technique: Iterations

Number of iterations: 1

Label: Hkappa eq

Components: All

Linear robust Direct

Nonlinear method:

Damoing factor:

Jacobian undate:

Matrix format: Automatic

Method and Termination

General

Variables

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• A simulation has been performed where we put a boundary condition of p = 1 Pa at the x = 0 inlet, and a "Sound Hard Boundary" on all other sides:









- The figure on the right shows the computed real part of the area-averaged presssure in the duct, for a frequency of 1 kHz.
- As visible, these models predict exactly the same pressure field.
- There is also an analytical solution for this case:

-

$$p(x) = \cos\left(\Gamma\left(L - x\right)\right) \quad (16)$$

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- Now we focus on a case were an exact solution is not available: the computation of the equivalent series impedance of a micro-perforate. The figure at the bottom shows a typical "unit cell", of a square pattern micro-perforate with circular holes. We solve this model for 20 frequencies. To reduce the number of DOFS, the symmetry allows to solve for 1/8 of the actual unit cell.
- We show results of wall clock time, as they count for us. There were no other tasks running on the machine.





- We use the following machine:
- Intel Xeon Silver 4214, 24 cores, 130 GiB RAM.
- The used solver is Pardiso.
- The number of DOFS is:
 - Pressure acoustics: 20,853 (Quadratic Lagrange)
 - Thermoviscous acoustics: 359,116 (Linear pressure, Quadratic Serendipity T, u)
- The table on the right shows the computation times for 20 frequencies.
- There are some other ways of gaining speedups:
 - Frequency-dependent mesh size
 - Decreasing the order of the shape functions (and increasing the mesh size locally where required).

	Thermoviscous acoustics	SLNS
Wall clock time	16m18s	1m50s
Speedup	1.0	9.2

October 25, 2023





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Dr.ii	r. Ani	ne d	e Jo	ng

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20/21

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- In this presentation we showed and derived the Sequentially Linearized Navier Stokes (SLNS) model, and the way it can be implemented in COMSOL.
- We have verified the correct implementation in COMSOL, and have showed that it is able to reach significant speedups for practical computations in micro-acoustics.
- Want to know more?
 - E: j.a.dejong@ascee.nl
 - ► T: +31 6 189 71 622
- Here are some references:
- W. Kampinga. "Viscothermal acoustics using finite elements: analysis tools for engineers." PhD thesis. Enschede, The Netherlands: University of Twente, 2010.
- [2] W. Kampinga, Y. Wijnant, and A. de Boer. "An Efficient Finite Element Model for Viscothermal Acoustics." In: Acta Acustica united with Acustica 97.4 (2011), pp. 618–631.
- [3] W. Kampinga, Y. Wijnant, and A. de Boer. "Performance of Several Viscothermal Acoustic Finite Elements." In: Acta Acustica united with Acustica 96.1 (2010), pp. 115–124.